

$$\begin{cases} Ox: -P \sin \theta - F_f = ma \rightarrow (1) \\ Oy: P \cos \theta - R_N = 0 \rightarrow (2) \end{cases}$$

de (1):  $-mg \sin \theta - \mu R_N = ma$  et de (2):  $mg \cos \theta = R_N$

$$\Rightarrow -mg \sin \theta - \mu mg \cos \theta = ma \Rightarrow -mg(\sin \theta + \mu \cos \theta) = ma$$

$$\Rightarrow a = -g(\sin \theta + \mu \cos \theta)$$

Sachons que :

$$a = \frac{dV}{dt} = \frac{dV}{dt} \frac{dx}{dx} = \frac{dV}{dx} \frac{dx}{dt} = V \frac{dV}{dx}$$

$$\Rightarrow V dV = -g(\sin \theta + \mu \cos \theta) dx \Rightarrow \int_{V_B}^V V dV = -g(\sin \theta + \mu \cos \theta) \int_0^x dx$$

$$\Rightarrow \frac{V^2}{2} \Big|_{V_B}^V = -g(\sin \theta + \mu \cos \theta) x \Big|_0^x \Rightarrow V^2 = -2g(\sin \theta + \mu \cos \theta) x + V_B^2$$

$$\Rightarrow V(M_2) = \sqrt{-2g(\sin \theta + \mu \cos \theta) x + V_B^2}$$

$$V_B \left( \theta = \frac{\pi}{2} \right) = \sqrt{2gR \sin \left( \frac{\pi}{2} \right) + V_0^2} = \sqrt{2gR + V_0^2}$$

$$\Rightarrow V(M_2) = \sqrt{-2g(\sin \theta + \mu \cos \theta) x + 2gR + V_0^2}$$

### 3. La vitesse au point d'arrivée C :

Au point d'arrivée C :  $x = l$

$$\Rightarrow V(C) = \sqrt{-2g(\sin \theta + \mu \cos \theta)l + 2gR + V_0^2}$$