

Condition Limite gauche de Neumann discrétisée par un schéma centré

```
> restart : with(LinearAlgebra) :
> L := 20; H := 20; ndx := 3; ndy := 3;
    L := 20
    H := 20
    ndx := 3
    ndy := 3
```

(1.1)

```
> Td := 10; Tb := 10; Th := 30; alpha := 0
    Td := 10
    Tb := 10
    Th := 30
    alpha := 0
```

(1.2)

```
> Delta_x := L/ndx; Delta_y := H/ndy; beta := Delta_x/Delta_y
    Delta_x := 20/3
    Delta_y := 20/3
    beta := 1
```

(1.3)

```
> i_max := ndx + 1; j_max := ndy + 1;
    i_max := 4
    j_max := 4
```

(1.4)

```
> N := (i_max - 2) * (j_max - 2) + j_max - 2;
    N := 6
```

(1.5)

```
> for j from 2 to j_max - 1 do T[i_max, j] := Td end do;
    T[4, 2] := 10
    T[4, 3] := 10
```

(1.6)

```
> for i from 1 to i_max - 1 do T[i, 1] := Tb end do;
    T[1, 1] := 10
    T[2, 1] := 10
    T[3, 1] := 10
```

(1.7)

```
> for i from 1 to i_max - 1 do T[i, j_max] := Th end do;
    T[1, 4] := 30
    T[2, 4] := 30
    T[3, 4] := 30
```

(1.8)

```

k := 1 :
  for j from 2 to jmax - 1 do
    T[0, j] := T[2, j] - 2·α·Δx :
    Eq[k] := - 2·(1 + β2)·T[1, j] + T[2, j] + T[0, j] + β2·(T[1, j + 1] + T[1, j - 1]) = 0 :
    Temps[k] := T[1, j] :
    k := k + 1 :
    for i from 2 to imax - 1 do
      Eq[k] := - 2·(1 + β2)·T[i, j] + T[i + 1, j] + T[i - 1, j] + β2·(T[i, j + 1] + T[i, j - 1]) = 0 :
      Temps[k] := T[i, j] :
      k := k + 1 :
    end do
  end do:

```

```

> for k from 1 to N do Eq[k] end do;
      -4 T1,2 + 2 T2,2 + T1,3 + 10 = 0
      -4 T2,2 + T3,2 + T1,2 + T2,3 + 10 = 0
      -4 T3,2 + 20 + T2,2 + T3,3 = 0
      -4 T1,3 + 2 T2,3 + 30 + T1,2 = 0
      -4 T2,3 + T3,3 + T1,3 + 30 + T2,2 = 0
      -4 T3,3 + 40 + T2,3 + T3,2 = 0

```

(1.9)

```

> N := k - 1;
      N := 6

```

(1.10)

```

> Eqs := {seq(Eq[k], k = 1 .. N)};
Eqs := {-4 T1,2 + 2 T2,2 + T1,3 + 10 = 0, -4 T1,3 + 2 T2,3 + 30 + T1,2 = 0, -4 T3,2 + 20
+ T2,2 + T3,3 = 0, -4 T3,3 + 40 + T2,3 + T3,2 = 0, -4 T2,2 + T3,2 + T1,2 + T2,3 + 10
= 0, -4 T2,3 + T3,3 + T1,3 + 30 + T2,2 = 0}

```

(1.11)

```

> Tmps := [seq(Temps[k], k = 1 .. N)];
      Tmps := [T1,2, T2,2, T3,2, T1,3, T2,3, T3,3]

```

(1.12)

```

> SolT := solve(Eqs, Tmps);
SolT := [[ T1,2 =  $\frac{1546}{99}$ , T2,2 =  $\frac{500}{33}$ , T3,2 =  $\frac{1334}{99}$ , T1,3 =  $\frac{2194}{99}$ , T2,3 =  $\frac{710}{33}$ , T3,3
=  $\frac{1856}{99}$  ]

```

(1.13)

```

> Eqs := [seq(Eq[k], k = 1 .. N)];
Eqs := [-4 T1,2 + 2 T2,2 + T1,3 + 10 = 0, -4 T2,2 + T3,2 + T1,2 + T2,3 + 10 = 0, -4 T3,2
+ 20 + T2,2 + T3,3 = 0, -4 T1,3 + 2 T2,3 + 30 + T1,2 = 0, -4 T2,3 + T3,3 + T1,3
+ 30 + T2,2 = 0, -4 T3,3 + 40 + T2,3 + T3,2 = 0]

```

(1.14)

```

> M, R := GenerateMatrix(Eqs, Tmps)

```

⌋

$$M, R := \begin{bmatrix} -4 & 2 & 0 & 1 & 0 & 0 \\ 1 & -4 & 1 & 0 & 1 & 0 \\ 0 & 1 & -4 & 0 & 0 & 1 \\ 1 & 0 & 0 & -4 & 2 & 0 \\ 0 & 1 & 0 & 1 & -4 & 1 \\ 0 & 0 & 1 & 0 & 1 & -4 \end{bmatrix}, \begin{bmatrix} -10 \\ -10 \\ -20 \\ -30 \\ -30 \\ -40 \end{bmatrix}$$

(1.15)